

Phase Transition for Glauber Dynamics for Independent Sets on Regular Trees

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Abstract

We study the effect of boundary conditions on the relaxation time (i.e., inverse spectral gap) of the Glauber dynamics for the hard-core model on the tree. The hard-core model is defined on the set of independent sets weighted by a parameter λ , called the activity or fugacity. The Glauber dynamics is the Markov chain that updates a randomly chosen vertex in each step. On the infinite tree with branching factor b , the hard-core model can be equivalently defined as a broadcasting process with a parameter ω which is the positive solution to $\lambda = \omega(1 + \omega)^b$, and vertices are occupied with probability $\omega/(1 + \omega)$ when their parent is unoccupied. This broadcasting process undergoes a phase transition between the so-called reconstruction and non-reconstruction regions at $\omega_r \approx \ln b/b$. Reconstruction has been of considerable interest recently since it appears to be intimately connected to the efficiency of local algorithms on locally tree-like graphs, such as sparse random graphs.

In this paper we show that the relaxation time of the Glauber dynamics on regular trees T_h of height h with branching factor b and n vertices, undergoes a phase transition around the reconstruction threshold. In particular, we construct a boundary condition for which the relaxation time slows down at the reconstruction threshold. More precisely, for any $\omega \leq \ln b/b$, for T_h with any boundary condition, the relaxation time is $\Omega(n)$ and $O(n^{1+o_b(1)})$. In contrast, above the reconstruction threshold we show that for every $\delta > 0$, for $\omega = (1 + \delta) \ln b/b$, the relaxation time on T_h with any boundary condition is $O(n^{1+\delta+o_b(1)})$, and we construct a boundary condition where the relaxation time is $\Omega(n^{1+\delta/2-o_b(1)})$. To prove this lower bound in the reconstruction region we introduce a general technique that transforms a reconstruction algorithm into a set with poor conductance.

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1 Introduction

There has been much recent interest in possible connections between equilibrium properties of statistical physics models and efficiency of local Markov chains for studying these models (see, e.g., [3, 10, 20, 21, 22, 30]). In this paper we study the hard-core model and establish new connections between the so-called reconstruction threshold in statistical physics with the convergence time of the single-site Markov chain known as the Glauber dynamics. The hard-core model was studied in statistical physics as model of a lattice gas (see, e.g., Sokal [29]), and in operations research as a model of communication network (see Kelly [15]). It is a natural combinatorial problem, corresponding to counting and randomly sampling weighted independent sets of an input graph $G = (V, E)$. Let $\Omega = \Omega(G)$ denote the set of independent sets of G . Each set is weighted by an activity (or fugacity) $\lambda > 0$. For $\sigma \in \Omega$, its weight is $Z(\sigma) = \lambda^{|\sigma|}$ where $|\sigma|$ is the number of vertices in the set σ . The Gibbs measure is defined over Ω as $\mu(\sigma) = Z(\sigma)/Z$ where $Z = \sum_{\sigma \in \Omega} Z(\sigma)$ is the partition function.

This paper studies the hard-core model on trees, in some cases with a boundary condition. Let T_h denote the complete tree of height h with branching factor b . For concreteness we are assuming the root has b children, but our results, of course, easily extend to allow $b+1$ children for the root, the so-called Bethe lattice. Let n denote the number of vertices in T_h , and let L denote the leaves of the tree. A boundary condition is an assignment Γ to the leaves, where in the case of the hard-core model, Γ specifies a subset of the leaves L that are in the independent set. Then let $\Omega_\Gamma = \{\sigma \in \Omega : \sigma(L) = \Gamma\}$ be the set of independent sets of T_h that are consistent with Γ , and the Gibbs measure $\mu_{h,\Gamma}$ is defined with respect to Ω_Γ , i.e., it is the projection of μ onto Ω_Γ .

The (heat bath) Glauber dynamics is a discrete time Markov chain (X_t) for sampling from the Gibbs distribution μ for a given graph $G = (V, E)$ and activity λ . We view $\Omega \subset \{0, 1\}^V$ where for $X_t \in \Omega$, $X_t(v) = 1$ iff v is in the independent set. The transitions $X_t \rightarrow X_{t+1}$ of the Glauber dynamics are defined as:

- Choose a vertex v uniformly at random;
- For all $w \neq v$ set $X_{t+1}(w) = X_t(w)$;
- If all of the neighbors of v are unoccupied, set $X_{t+1}(v) = 1$ with probability $\lambda/(1+\lambda)$, otherwise set $X_{t+1}(v) = 0$.

When a boundary condition Γ is specified, the state space is restricted to Ω_Γ . For the case of the complete tree T_h (possibly with a boundary condition Γ) it is straightforward to verify that the Glauber dynamics is ergodic with unique stationary distribution μ_h (or $\mu_{h,\Gamma}$ when a boundary condition is specified). Thus, the Glauber dynamics is a natural algorithmic process for sampling from the Gibbs distribution. We study the relaxation time of the dynamics, which is defined as the inverse of the spectral gap of the transition matrix. See Section 2 for a more detailed definition of the relaxation time.

The Gibbs distribution describes the equilibrium state of the system, and the Glauber dynamics is a model of how the physical system reaches equilibrium [20]. Thus, it is interesting to understand connections between properties of the equilibrium state (i.e., the Gibbs distribution) and properties of how the system reaches equilibrium (i.e., the Glauber dynamics). Models from statistical physics are designed to study phase transitions

in the equilibrium state. A phase transition is said to occur when a small change in the microscopic parameters of the system (in the case of the hard-core model that corresponds to λ) causes a dramatic change in the macroscopic properties of the system.

A well-studied phase transition is uniqueness/non-uniqueness of infinite volume Gibbs distributions, these are obtained as a limit of Gibbs measures for a sequence of boundary conditions as $h \rightarrow \infty$. For the hard-core model on the complete tree, Kelly [15] showed that the uniqueness threshold is at $\lambda_u = b^b/(b-1)^{b+1}$ (namely, uniqueness holds iff $\lambda < \lambda_u$). There are interesting connections between the uniqueness threshold λ_u and the efficiency of algorithms on general graphs. In particular, Weitz [31] showed a deterministic fully-polynomial approximation scheme to estimate the partition function for any graph with constant maximum degree b for activities $\lambda < \lambda_u$. Recently, Sly [28] showed that it is NP-hard (unless $NP = RP$) to approximate the partition function for activities λ satisfying $\lambda_u < \lambda < \lambda_u + \epsilon_b$ for some small constant ϵ_b .

We are interested in the phase transition for reconstruction/non-reconstruction. This corresponds to extremality of the infinite-volume measure obtained by the “free” boundary condition where free means no boundary condition [11]. This measure can be generated by the following broadcast process which constructs an independent set σ . Let ω be the real positive solution of $\lambda = \omega(1 + \omega)^b$. Consider the infinite complete tree with branching factor b , and construct σ as follows. We first include the root r in σ with probability $\omega/(1 + \omega)$ and leave it out with probability $1/(1 + \omega)$. Then for each vertex v , once the state of its parent $p(v)$ is determined, if $p(v) \notin \sigma$ then we add v into σ with probability $\omega/(1 + \omega)$ and leave it out with probability $1/(1 + \omega)$; if $p(v) \in \sigma$ then we leave v out of σ . Let σ_h denote the configuration of σ on level h , and let ν_h denote the broadcast measure on T_h .

Reconstruction addresses whether σ_h “influences” the configuration at the root r . In words, we first generate σ using the broadcasting measure, then we fix σ_h and resample a configuration τ on T_h from the Gibbs distribution $\mu_{h,\Gamma}$ with boundary condition $\Gamma = \sigma_h$. Of course, for finite h , the configuration at the root r in τ has a bias to the initial configuration $\sigma(r)$. Non-reconstruction is said to hold if the root is unbiased in expectation in the limit $h \rightarrow \infty$. More precisely, reconstruction holds if and only if:

$$\lim_{h \rightarrow \infty} \mathbb{E}_{\sigma \sim \nu_h} \left[\left| \mu_{h,\sigma_h}(r \in \tau) - \frac{\omega}{1 + \omega} \right| \right] > 0. \quad (1)$$

There are many other equivalent conditions to the above definition of reconstruction, see Mossel [24] for a more extensive survey. We refer to the reconstruction threshold as the critical ω_r such that for all $\omega < \omega_r$ non-reconstruction holds and for all $\omega > \omega_r$ reconstruction holds. The existence of the reconstruction threshold follows from Mossel [25, Proposition 20], and, by recent work of Bhatnagar et al [4] and Brightwell and Winkler [6], it is known that $\omega_r = (\ln b + (1 + o(1)) \ln \ln b)/b$.

Reconstruction for the Ising and Potts models has applications in phylogenetics [8] and for random constraint satisfaction problems is connected to the geometry of the space of solutions on sparse random graphs [1, 12, 16, 23]. Our interest in this paper is on establishing more detailed connections between the reconstruction threshold and the relaxation time of the Glauber dynamics for trees. Berger et al [3] proved that for the tree T_h with boundary condition Γ such that $\mu_{h,\Gamma} = \nu_h$, $O(n)$ relaxation time for all h implies non-reconstruction. For the Ising model and colorings the boundary condition is empty,

i.e., ν_h corresponds to the free boundary condition. That is not the case for the hard-core model as discussed further in Section 3.

It was recently established for the Ising model [3, 21, 7] and for k -colorings [30] that on the tree T_h with free boundary condition, the relaxation is $O(n)$ in the non-reconstruction region and there is a slow down in the reconstruction region. Our starting point was addressing whether a similar phenomenon occurs in the hard-core model. Martinelli et al [22] showed that for the hard-core model on T_h with free boundary condition the relaxation time is $O(n)$ for all λ (and the mixing time is $O(n \log n)$). However, it is unclear whether the reconstruction threshold has any connection to the relaxation time of the Glauber dynamics on trees for the hard-core model. (In fact, we vacillated between proving that there is fast mixing for all boundary conditions and proving the following result.)

We prove there is a connection by constructing a boundary condition for which the relaxation time slows down at the reconstruction threshold. Here is the formal statement of our results.

Theorem 1. *For the Glauber dynamics on the hard-core model with activity $\lambda = \omega(1+\omega)^b$ on the complete tree T_h with n vertices, height h and branching factor b , the following hold:*

1. **For all $\omega \leq \ln b/b$:**

$$\Omega(n) \leq T_{\text{relax}} \leq O(n^{1+o_b(1)}).$$

2. **For all $\delta > 0$ and $\omega = (1 + \delta) \ln b/b$:**

(a) *For every boundary condition,*

$$T_{\text{relax}} \leq O(n^{1+\delta+o_b(1)}).$$

(b) *There exists a sequence of boundary conditions for all $h \rightarrow \infty$ such that,*

$$T_{\text{relax}} = \Omega(n^{1+\delta/2-o_b(1)}).$$

Remark. More precisely, we show that there is a function $g(b) = O(\ln \ln b / \ln b) = o(1)$ such that for every b , the lower bound in Part 2b is $\Omega(n^{1+\delta/2-g(b)})$, and there is a function $f(b) = O((\ln \ln b)^2 / \ln b) = o(1)$ such that for every b , the upper bound in Part 1 is $O(n^{1+f(b)})$ and in Part 2a is $O(n^{1+\delta+f(b)})$.

The upper bound improves upon Martinelli et al [22] who showed $O(n)$ relaxation time (and $O(n \log n)$ mixing time) for $\lambda < 1/(\sqrt{b} - 1)$ for all boundary conditions. Note, $\lambda = 1/\sqrt{b}$ is roughly equivalent to $\omega \approx \frac{1}{2} \ln b/b$ which is below the reconstruction threshold. Our main result extends the fast mixing up to the reconstruction threshold, and shows the slow-down beyond the reconstruction threshold. Our lower bound in the reconstruction region uses a general approach that transforms an algorithm showing reconstruction into a set with poor conductance, which implies the lower bound on the relaxation time. This framework captures the proof approach used in [30].

In Section 2 we formally define various terms and present the basic tools used in our proofs. The lower bound (Part 2b of Theorem 1) is presented in Sections 3, 4 and 5. Section 3 outlines the approach. We then prove an analogue of Theorem 1 in Section 4 for the broadcasting model and use it in Section 5 to prove Part 2b of Theorem 1. The argument for the upper bounds stated in Theorem 1 is presented in Section 6.

2 Background

Let $P(\cdot, \cdot)$ denote the transition matrix of the Glauber dynamics. Let $\gamma_1 \geq \gamma_2 \geq \dots \geq \gamma_{|\Omega|}$ be the eigenvalues of the transition matrix P . The spectral gap c_{gap} is defined as $1 - \gamma$ where $\gamma = \max\{\gamma_2, |\gamma_{|\Omega|}|\}$ denotes the second largest eigenvalue in absolute value. The relaxation time T_{relax} of the Markov chain is then defined as c_{gap}^{-1} , the inverse of the spectral gap. Relaxation time is an important measure of the convergence rate of a Markov chain (see, e.g., Chapter 12 in [18]).

To lower bound the relaxation time we analyze conductance. The conductance of a Markov chain with state space Ω and transition matrix P is given by $\Phi = \min_{S \subseteq \Omega} \{\Phi_S\}$, where Φ_S is the conductance of a specific set $S \subseteq \Omega$ defined as

$$\Phi_S = \frac{\sum_{\sigma \in S} \sum_{\eta \in \bar{S}} \pi(\sigma) P(\sigma, \eta)}{\pi(S) \pi(\bar{S})}.$$

Thus, a general way to find a good upper bound on the conductance is to find a set S such that the probability of “escaping” from S is relatively small. The well-known relationship between the relaxation time and the conductance was established in [17] and [26], and we will use the form $T_{\text{relax}} = \Omega(1/\Phi)$ for proving the lower bounds.

3 Lower Bound Approach

First note that the lower bound stated in Part 1 of Theorem 1, namely, $T_{\text{relax}} = \Omega(n)$, is trivial for all ω . For example, by considering the set $S = \{\sigma \in \Omega : r \notin \sigma\}$ of independent sets which do not contain the root, $\Phi(S) = \Omega(1/n)$ since we need to update r to leave S .

We begin by explaining the high level idea of the non-trivial lower bound in Part 2b of Theorem 1. To that end, we first analyze a variant of the hard-core model in which there are two different activities, the internal vertices have activity λ and the leaves have activity ω . The resulting Gibbs distribution is identical to the measure ν_h defined in Section 1 for the broadcasting process. Thus we refer to the following model as the broadcasting model.

For the tree $T_h = (V, E)$, we look at the following equivalent definition of the distribution ν_h over the set Ω of independent sets of T_h . For $\sigma \in \Omega$, let

$$Z'(\sigma) = \lambda^{|\sigma \cap V \setminus L|} \omega^{|\sigma \cap L|},$$

where L are the leaves of T_h and ω is, as before, the positive solution to $\omega(1 + \omega)^b = \lambda$. Let $\nu_h(\sigma) = Z'(\sigma)/Z'$ where $Z' = \sum_{\sigma \in \Omega} Z'(\sigma)$ is the partition function. By simple calculations, the following proposition holds.

Proposition 2. *The measure ν_h defined by the hard-core model with activity λ for internal vertices and ω for leaves is identical to the measure defined by the broadcasting process.*

Proof. In fact, we just need to verify that in the hard-core model with activity λ for internal vertices and ω for leaves, the probability p_v of a vertex v being occupied conditioning on its parent is unoccupied is $\omega/(1 + \omega)$. This can be proved by induction. The base case is

v being a leaf, which is obviously true by the Markovian property of the Gibbs measure. If v is not a leaf, by induction, the probability p_v has to satisfy the following equation

$$p_v = (1 - p_v) \frac{\lambda}{(1 + \omega)^b},$$

which solves to $p_v = \omega/(1 + \omega)$. \square

The result of Berger et al [3] mentioned in Section 1 implies that the relaxation time of the Glauber dynamics on the broadcasting model is $\omega(n)$. We will prove a stronger result, analogous to the desired lower bound for Part 2b of Theorem 1.

Theorem 3. *For all $\delta > 0$, the Glauber dynamics for the broadcasting model on the complete tree T_h with n vertices, branching factor b and $w = (1 + \delta) \ln b/b$ satisfies the following:*

$$T_{\text{relax}} = \Omega(n^{1+\delta/2-o_b(1)}),$$

where the $o_b(1)$ function is $O(\ln \ln b / \ln b)$.

Remark. We can show a similar upper bound on the relaxation time for the Glauber dynamics in this setting as in Theorem 1. Moreover, we can show the same upper bound for the mixing time by establishing a tight bound between the inverse log-Sobolev constant and the relaxation time as was done for colorings in Tetali et al [30].

We will prove Theorem 3 via a general method that relates any reconstruction algorithm (or function) with the conductance of the Glauber dynamics. A *reconstruction algorithm* is a function $A : \Omega(L) \rightarrow \{0, 1\}$ (ideally efficiently computable) such that $A(\sigma_h)$ and $\sigma(r)$ are positively correlated. Basically, the algorithm A takes the configurations at the leaves L as the input and tries to compute the configuration at the root. When the context is clear, we write $A(\sigma)$ instead of $A(\sigma_h)$. Under the Gibbs measure ν_h , the *effectiveness* of A is the following measure of the covariance between the algorithm A 's output and the marginal at the root of the actual measure:

$$r_{h,A} = \min_{x \in \{0,1\}} [\nu_h(A(\sigma) = \sigma(r) = x) - \nu_h(A(\sigma) = x)\nu_h(\sigma(r) = x)].$$

If it is the case that $\liminf_{h \rightarrow \infty} r_{h,A} = c_0 > 0$ for some positive constant c_0 depending only on ω and b , then we say that it is an *effective reconstruction algorithm*. In words, an effective algorithm, is able to recover the spin at the root, from the information at the leaves, with a nontrivial success, when $h \rightarrow \infty$. Notice that reconstruction (defined in (1)) is a necessary condition for any reconstruction algorithm to be effective, since

$$\mathbb{E}_{\sigma \sim \nu_h} \left[\left| \mu_{h,\sigma_h}(r \in \tau) - \frac{\omega}{1 + \omega} \right| \right] \geq \mathbb{E}_{\sigma \sim \nu_h} [(\mu_{h,\sigma_h}(r \in \tau) - \nu_h(r \in \sigma)) \mathbf{1}(A(\sigma) = 1)] \geq r_{h,A},$$

where $\mathbf{1}()$ is the indicator function. We define the *sensitivity* of A , for the configuration $\sigma \in \Omega(T_h)$, as the fraction of vertices v such that switching the spin at v in σ changes the final result of A . More precisely, let σ^v be the configuration obtained from changing σ at v . Define the sensitivity as:

$$S_A(\sigma) = \frac{1}{n} \#\{v \in L : A(\sigma^v) \neq A(\sigma)\}.$$

The *average sensitivity* (with respect to the root being occupied) \bar{S}_A is hence defined as

$$\bar{S}_A = \mathbb{E}_{\sigma \sim \nu_h} [S_A(\sigma) \mathbf{1}(A(\sigma) = 1)].$$

It is fine to define the average sensitivity without the indicator function, which only affects a constant factor in the analysis. We are doing so to simplify some of the results' statements and proofs.

Typically when one proves reconstruction, it is done by presenting an effective reconstruction algorithm. Using the following theorem, by further analyzing the sensitivity of the reconstruction algorithm, one obtains a lower bound on the relaxation time or mixing time of the Glauber dynamics.

Theorem 4. *Suppose that A is an effective reconstruction algorithm. Then, the relaxation time T_{relax} of the Glauber dynamics satisfies $T_{\text{relax}} = \Omega((\bar{S}_A)^{-1})$.*

Remark. The above theorem can be generalized to any spin system. To illustrate the usefulness of this theorem, we note that the lower bound on the mixing time of the Glauber dynamics for k -colorings in the reconstruction region proved in [30] fits this conceptually appealing framework.

Proof. Throughout the proof let $\nu := \nu_h$. Consider the set $U = \{\sigma : A(\sigma) = 1\}$. Then,

$$\Phi_U = \frac{\sum_{\sigma \in U} \nu(\sigma) \sum_{w \in L} \sum_{\tau: \tau(w) \neq \sigma(w)} P(\sigma, \tau)}{\nu(U)(1 - \nu(U))} \leq \frac{\sum_{\sigma \in U} \nu(\sigma) S_A(\sigma)}{\nu(U)(1 - \nu(U))}.$$

From the definition of $r_{h,A}$, we have that $\nu(U) \geq \nu(A(\sigma) = \sigma(r) = 1) \geq r_{h,A}$, and similarly $(1 - \nu(U)) \geq \nu(A(\sigma) = \sigma(r) = 0) \geq r_{h,A}$. Now, because the algorithm is effective, we have $\liminf_{h \rightarrow \infty} (r_{h,A}) = c_0 > 0$ and hence for all h big enough, $r_{h,A} > 0$. Therefore, $\Phi_U \leq (r_{h,A})^{-2} \bar{S}_A$, which concludes that $T_{\text{relax}} = c_{\text{gap}}^{-1} \geq 1/\Phi_U = \Omega((\bar{S}_A)^{-1})$. \square

To prove Theorem 3, we analyze the sensitivity of the reconstruction algorithm by Brightwell and Winkler [6, Section 5] which yields the best known upper bounds on the reconstruction threshold. Our goal is to show that the average sensitivity of this algorithm is small. The analysis of the sensitivity of the Brightwell-Winkler (BW) algorithm, which then proves Theorem 3, is presented in Section 4.

Our main objective remains of constructing a sequence of “bad” boundary conditions under which the Glauber dynamics for the hard-core model slows down in the reconstruction region. An initial approach is that if we can find a complete tree T' with some boundary condition such that the marginal of the root being occupied exactly equals $\omega/(1 + \omega)$, then by attaching the same tree T' with the corresponding boundary conditions to all of the leaves of a complete tree T , we are able to simulate the nonuniform hard-core model on T , (i.e., the resulting measure projected onto T is the same as the one in the broadcasting model) and hence we can do the same approach to upper-bound the conductance of the dynamics on this new tree. However, from a cardinality argument, not for every ω there exists a complete tree of finite height with some boundary condition such that the marginal probability of the root being occupied equals $\omega/(1 + \omega)$. Alternatively, we give a constructive way to find boundary conditions that approximate the desired marginal probability relatively accurately. This is done in Section 5.

Finally, at the end of Section 5 we argue that since the error is shrinking very fast from the bottom level under our construction of boundary conditions, we can again analyze the sensitivity of the Brightwell-Winkler algorithm starting from just a few levels above the leaves. This approach yields the lower bound stated in Part 2b of Theorem 1.

4 Lower Bound for Broadcasting: Proof of Theorem 3

Throughout this section we work on the broadcasting model. To prove Theorem 3 we analyze the average sensitivity of the reconstruction algorithm used by Brightwell and Winkler [6], which we refer to as the BW algorithm. For any configuration σ as the input, the algorithm works in a bottom up manner labeling each vertex from the leaves: a parent is labeled to occupied if all of its children are labeled to unoccupied; otherwise, it is labeled to unoccupied. The algorithm will output the labeling of the root as the final result. Formally, it can be described by the following deterministic recursion deciding the labeling of every vertex:

$$R_\sigma(v) = \begin{cases} \sigma(v) & \text{if } v \in L \\ 1 - \max\{R_\sigma(w_1), R_\sigma(w_2), \dots, R_\sigma(w_b)\} & \text{otherwise} \end{cases}$$

where w_1, \dots, w_b are the children of v . Finally, let $\text{BW}(\sigma) = \text{BW}(\sigma_h) = R_\sigma(r)$. Note that, $\text{BW}(\sigma)$ only depends on the configuration σ_h on the leaves. The algorithm is proved to be effective in [6] when $\delta > 0$. Therefore, it can be used in our case to lower bound the relaxation time. In this algorithm, by definition we have

$$\bar{S}_{\text{BW}} = O(n^{-1} \mathbb{E}_{\sigma \sim \nu_h} [\#\{v \in L : \text{BW}(\sigma) = 1 \text{ and } \text{BW}(\sigma^v) = 0\}]), \quad (2)$$

Due to the symmetry of the function $R_\sigma(v)$ and the measure ν_h , the expectation can be further simplified as

$$\mathbb{E}_\sigma [\#\{v \in L : \text{BW}(\sigma) = 1 \text{ and } \text{BW}(\sigma^v) = 0\}] = b^h \nu_h(\text{BW}(\sigma) = 1 \text{ and } \text{BW}(\sigma^{\hat{u}}) = 0), \quad (3)$$

where \hat{u} is now a fixed leaf. To bound the right hand side of Eq.(3), let $\kappa \in \Omega(T_h)$ be a fixed configuration such that $\text{BW}(\kappa) = 1$. Let the path \mathcal{P} from \hat{u} to the root r be $u_0 = \hat{u} \rightsquigarrow u_1 \rightsquigarrow \dots \rightsquigarrow u_h = r$, and for any $i > 0$, let $w_{i,j}$ be the children of u_i so that the labeling is such that for $j = 1$, $w_{i,1} = u_{i-1}$ and for $j \neq 1$, $w_{i,j}$ is not on the path \mathcal{P} . An important observation is that, in order to make $\text{BW}(\kappa)$ change to 0 by changing only the configuration at \hat{u} of κ , a necessary condition for κ is $R_\kappa(u_i) = 1 - R_\kappa(u_{i-1})$ for all $i \geq 1$. Then for all $i \geq 1$ and $j \in \{2, \dots, b\}$, we have $R_\kappa(w_{i,j}) = 0$. To calculate the probability that a random $\kappa \sim \nu_h$ satisfies such conditions, it would be easier if we expose the configurations along the path \mathcal{P} . Since then, conditioning on the configurations on the path, the events $R_\kappa(w_{i,j}) = 0$ are independent for all i, j . And if $\kappa(u_i) = 0$, we have for all $j > 1$, the conditional probability of $R_\kappa(w_{i,j}) = 0$ equals $\Pr_{\eta \sim \nu_{i-1}} [\text{BW}(\eta) = 0]$, the probability BW algorithm outputs a 0 over a random configuration η of the leaves of the complete tree T_{i-1} with height $i - 1$. The analysis above leads to the following lemma, which bounds the probability $\nu_h(\text{BW}(\sigma) = 1 \text{ and } \text{BW}(\sigma^{\hat{u}}) = 0)$.

Lemma 5. *For every $i > 0$, let $\eta \in \Omega(T_{i-1})$ be a configuration chosen randomly according to measure ν_{i-1} , then*

$$\nu_h(BW(\sigma) = 1 \text{ and } BW(\sigma^{\hat{u}}) = 0) \leq \mathbb{E}_{\kappa \sim \nu_h} \left[\prod_{i>0: \kappa(u_i)=0} \Pr_{\eta \sim \nu_{i-1}} [BW(\eta) = 0]^{(b-1)} \right].$$

Complete proofs of lemmas in this section are deferred to Section 4.1. To use Lemma 5, we derive the following uniform bound on the probability $\Pr_{\eta \sim \nu_i} [BW(\eta) = 0]$, for all i . Here and through out the paper, $b_0(\delta)$ is a function explicitly defined in Lemma 8 in Section 4.2. This function is of order $\exp(\delta^{-1} \ln(\delta^{-1}))$ as $\delta \rightarrow 0$ and remains bounded as $\delta \rightarrow \infty$.

Lemma 6. *Let $\delta > 0$, and let $\omega = (1 + \delta) \ln b/b$. For all $b \geq b_0(\delta)$ and $i \geq 1$,*

$$\Pr_{\eta \sim \nu_i} [BW(\eta) = 0] \leq \frac{(1.01)^{1/b}}{1 + \omega}.$$

Combining Equations (2), (3), Lemma 5 and Lemma 6, we are able to upper bound the average sensitivity of the BW algorithm:

$$\bar{S}_{BW} = O(\nu_h(BW(\sigma) = 1 \text{ and } BW(\sigma^{\hat{u}}) = 0)) = O \left(\mathbb{E}_{\kappa \sim \nu_h} \left[\left(\frac{1.01\omega(1+\omega)}{\lambda} \right)^{\#\{i: \kappa(u_i)=0\}} \right] \right).$$

In this expectation, the number of unoccupied vertices in the path \mathcal{P} can be trivially lower bounded by $h/2$, since it is impossible that there exists $i > 0$, $\kappa(u_i) = \kappa(u_{i-1}) = 1$. Therefore, the above expectation can be easily bounded by $O^*(n^{-(1+\delta)/2})$. This is not good enough in our case. We sharpen the bound using Lemma 9 in Section 4.2, leading to the following theorem, whose complete proof is contained in Section 4.1.

Theorem 7. *Let $\delta > 0$, and let $\omega = (1 + \delta) \ln b/b$. For all $b \geq b_0(\delta)$,*

$$T_{\text{relax}} = \Omega(n^d), \quad \text{where } d = \left(1 + \frac{\ln(\lambda/(1.01\omega b)^2)}{2 \ln b} \right).$$

Theorem 3 is a simple corollary of Theorem 7 by noticing that $d = 1 + \delta/2 - O(\frac{\ln \ln b}{\ln b})$. Furthermore, we can “hide” the fact that $b \geq b_0(\delta)$ in this residual term, by using the trivial lower bound $\Omega(n)$ for all $b < b_0(\delta)$ and $b_0(\delta) \approx \exp(\delta^{-1} \ln(\delta^{-1}))$ as $\delta \rightarrow 0$.

4.1 Proofs.

Note that throughout this paper, we will use the following notations for the relationships between two functions $f(x)$ and $g(x)$ for simplicity. If $\lim_{x \rightarrow \infty} f(x)/g(x) = 1$, we write $f(x) \approx g(x)$; if $f(x) = O(g(x))$, we write $f(x) \lesssim g(x)$ and if $f(x) = \Omega(g(x))$, we write $f(x) \gtrsim g(x)$.

Proof of Lemma 5. Let $\mathbf{x} = \{0, 1\}^h$ be a valid configuration on the path \mathcal{P} . Conditioning on $\kappa(u_i) = \mathbf{x}(i)$ for all i , we know that the events $R_{\kappa}(w_{i,j}) = 0$ are independent for all i and j . Given $\kappa(u_i) = 0$, the probability of the event $R_{\kappa}(w_{i,j}) = 0$ equals $\Pr_{\eta \sim \nu_{i-1}} [BW(\eta) = 0]$;

and given $\kappa(u_i) = 1$, the probability of this event can be trivially upper bounded by 1 (this bound is “safe”, in the sense that the actual quantity is close to 1 for big λ). By this, we can conclude that

$$\begin{aligned} & \nu_h(\text{BW}(\kappa) = 1 \text{ and } \text{BW}(\kappa^{\hat{u}}) = 0) \\ & \leq \sum_{\mathbf{x}} \nu_h(\kappa : \forall i, \kappa(u_i) = \mathbf{x}(u_i)) \prod_{i>0: \kappa(u_i)=0} \Pr_{\eta \sim \nu_{i-1}} [\text{BW}(\eta) = 0]^{(b-1)} \\ & = \mathbb{E}_{\kappa} \left[\prod_{i>0: \kappa(u_i)=0} \Pr_{\eta \sim \nu_{i-1}} [\text{BW}(\eta) = 0]^{(b-1)} \right]. \end{aligned}$$

□

Proof of Lemma 6. In the proof, we will use the fact that $\exp\left(\frac{2(1.01)(\omega b)^2}{\lambda}\right) \leq 1.01$, whenever $b \geq b_0(\delta)$ (Lemma 8). Now, for simplicity, denote $f_i = \Pr_{\eta \sim \nu_{i-1}} [A(\eta) = 0]$. First of all, notice the recurrences

$$\begin{aligned} f_{i+1} &= \frac{\omega}{1+\omega} \left(1 - \left(1 - f_{i-1}^b \right)^b \right) + \frac{1}{1+\omega} \left(1 - f_i^b \right), \\ f_1 &= \frac{1}{1+\omega} \quad , \quad f_2 = \frac{1}{1+\omega} \left(1 - \left(\frac{1}{1+\omega} \right)^b \right). \end{aligned}$$

The result follows by an easy induction: For $h = 1, 2$, the result is clear. On the other hand, from the previous recurrences, if it is the case that $f_i \leq \frac{(1.01)^{1/b}}{1+\omega}$, then

$$\begin{aligned} f_{i+1}^b &\leq \left[\frac{\omega}{1+\omega} \left(1 - \left(1 - f_{i-1}^b \right)^b \right) + \frac{1}{1+\omega} \right]^b \\ &\leq \left[\frac{\omega}{1+\omega} \left(1 - \left(1 - \frac{1.01\omega}{\lambda} \right)^b \right) + \frac{1}{1+\omega} \right]^b \\ &\leq \left(\frac{1 + \frac{1.01\omega^2 b}{\lambda}}{1+\omega} \right)^b \leq \frac{\exp(1.01(\omega b)^2/\lambda)}{(1+\omega)^b} \leq \frac{1.01}{(1+\omega)^b}, \end{aligned}$$

where the third inequality follows from the fact that $(1-u)^b \geq 1-ub$ for $u < 1$, the fourth inequality follows from $(1+u) \leq e^u$, and the last inequality follows from the fact that $\exp\left(\frac{2(1.01)(\omega b)^2}{\lambda}\right) \leq 1.01$ for $b \geq b_0(\delta)$. □

Proof of Theorem 7. From Lemma 9 in Section 4.2, we have that

$$\mathbb{E} \left[\left(\frac{1.01\omega(1+\omega)}{\lambda} \right)^{\#\{i: \sigma(u_i)=0\}} \right] \approx \left(1 + \frac{1-\epsilon}{2\epsilon(1+\omega)} \right) \frac{(1+\epsilon)}{2} \left(\frac{1.01\omega}{2\lambda} \left[1 + \sqrt{1 + 4\lambda/1.01} \right] \right)^h$$

where $\epsilon = \left[\sqrt{1 + 4\lambda/1.01} \right]^{-1}$. The previous term is asymptotically dominated by $\left(1.01 \frac{\omega}{\lambda^{1/2}} \right)^h$. Therefore,

$$\bar{S}_A = O \left(\left[\frac{1.01\omega}{\lambda^{1/2}} \right]^h \right) = O \left(n^{-\left[1 + \frac{\ln(\lambda/(1.01\omega b)^2)}{2 \ln b} \right]} \right).$$

Now, from [6, Section 5], it is known that the BW algorithm is effective for $\omega > (1 + \delta) \ln b/b$ and $b > b_0(\delta)$. (This can also be deduced from Lemma 6 by following the same steps as in Proposition 16), therefore Theorem 4 applies. The conclusion follows. \square

4.2 Some Technical Lemmas.

Lemma 8. Define $b_0(\delta) = \min\{b_0 : \exp\left(\frac{2(1.01)(\omega b)^2}{\lambda}\right) \leq 1.01 \text{ for all } b \geq b_0\}$. Then $b_0(\delta)$ is a continuous function such that

1. $b_0(\delta) < \infty$ for all $\delta > 0$ (that is, it is well defined).
2. $b_0(\delta) \approx \exp((1 + o(1))\delta^{-1} \ln(\delta^{-1}))$ as $\delta \rightarrow 0$.
3. $b_0(\delta) \approx b_0(\infty)$ as $\delta \rightarrow \infty$, where $b_0(\infty)$ is a fixed constant ≤ 2 .

Proof. For (1), just notice that for $\delta > 0$ fixed, we have that, as $b \rightarrow \infty$,

$$\exp\left(\frac{2(1.01)(\omega b)^2}{\lambda}\right) \approx 1 < 1.01.$$

For (2), notice that if we let $b = \exp(\beta\delta^{-1} \ln(\delta^{-1}))$, then as $\delta \rightarrow 0$, we have that

$$\exp\left(\frac{2(1.01)(\omega b)^2}{\lambda}\right) \approx \exp\left(2(1.01)\beta\delta^{\beta-1} \ln(\delta^{-1})\right).$$

Therefore, if $\beta \leq 1$, it is the case that $\exp\left(\frac{2(1.01)(\omega b)^2}{\lambda}\right) \rightarrow \infty$ as $\delta \rightarrow 0$, while if $\beta > 1$ the same expression goes to 1.

For (3), notice that for b fixed, $\exp\left(\frac{2(1.01)(\omega b)^2}{\lambda}\right) \approx \exp\left(\frac{\Theta(1)}{\delta^{b-1}}\right)$, as $\delta \rightarrow \infty$. \square

Lemma 9. Let ζ_0, ζ_1, \dots be a Markov process with state space $\{0, 1\}$, such that $\zeta_0 = 0$ and with transition rates $p_{0 \rightarrow 0} = p$, $p_{0 \rightarrow 1} = q$, $p_{1 \rightarrow 0} = 1$, $p_{1 \rightarrow 1} = 0$. Let $N_h = \#\{1 \leq i \leq h : \zeta_i = 0\}$, then

$$\mathbb{E}[a^{N_h}] \approx \left(1 + \frac{p(1-\epsilon)}{2\epsilon}\right) \frac{(1+\epsilon)}{2} \left(\frac{pa}{2} \left[1 + \sqrt{1 + 4q/(ap^2)}\right]\right)^h.$$

where $\epsilon = \frac{1}{\sqrt{1+4q/(ap^2)}}$. Moreover, if the transition rate $p_{0 \rightarrow 0}$ is inhomogeneous but such that $|p - p_{0 \rightarrow 0}^{(i)}| \leq \delta$, then

$$\mathbb{E}[a^{N_h}] \lesssim \left(1 + \frac{(p+\delta)(1-\bar{\epsilon})}{2\bar{\epsilon}}\right) \frac{(1+\bar{\epsilon})}{2} \left(\frac{(p+\delta)a}{2} \left[1 + \sqrt{1 + 4(q+\delta)/(a(p+\delta)^2)}\right]\right)^h,$$

where $\bar{\epsilon} = \frac{1}{\sqrt{1+4(q+\delta)/(a(p+\delta)^2)}}$.

Proof. Straightforward combinatorics leads to the expression

$$\mathbb{E}[a^{N_h}] = \sum_{k=0}^{\lfloor h/2 \rfloor} \binom{h-k}{k} p^{h-2k} q^k a^{h-k} + \sum_{k=1}^{\lfloor (h+1)/2 \rfloor} \binom{h-k}{k-1} p^{h-2k+1} q^k a^{h-k}$$

Now, for the first term, we have that

$$\sum_{k=0}^{\lfloor h/2 \rfloor} \binom{h-k}{k} p^{h-2k} q^k a^{h-k} = (pa)^h \sum_{k=0}^{\lfloor h/2 \rfloor} \binom{h-k}{k} x^k,$$

where $x = \frac{q}{ap^2}$, which by standard saddle point methods, noticing that the function $\phi(t) = \lim_{h \rightarrow \infty} h^{-1} \ln \left[\binom{h-th}{th} x^{th} \right]$ reaches its maximum at the point $t^* = \frac{1}{2}(1 - \epsilon)$, where $\epsilon = 1/\sqrt{1+4x}$ and $\phi''(t^*) = \sqrt{\frac{4}{\epsilon(1-\epsilon)(1+\epsilon)}}$, implying that

$$\frac{1}{(pa)^h} \sum_{k=0}^{\lfloor h/2 \rfloor} \binom{h-k}{k} p^{h-2k} q^k a^{h-k} \approx \frac{(1+\epsilon)}{2} \left(\frac{1+\sqrt{1+4x}}{2} \right)^h.$$

Similarly,

$$\frac{1}{(pa)^h} \sum_{k=1}^{\lfloor (h+1)/2 \rfloor} \binom{h-k}{k-1} p^{h-2k+1} q^k a^{h-k} \approx \frac{p(1-\epsilon)}{2\epsilon} \frac{(1+\epsilon)}{2} \left(\frac{1+\sqrt{1+4q/(ap^2)}}{2} \right)^h,$$

from where the result follows. In the inhomogeneous case, we have that

$$\mathbb{E}[a^{N_h}] \leq \sum_{k=0}^{\lfloor h/2 \rfloor} \binom{h-k}{k} (p+\delta)^{h-2k} (q+\delta)^k a^{h-k} + \sum_{k=1}^{\lfloor (h+1)/2 \rfloor} \binom{h-k}{k-1} (p+\delta)^{h-2k+1} (q+\delta)^k a^{h-k},$$

from where the result follows using the same asymptotic. \square

5 “Bad” Boundary Conditions: Proof of Theorem 1.2b

First, we will show that for any ω , there exists a sequence of boundary conditions, denoted as $\Gamma_\omega := \{\Gamma_i\}_{i>0}$, one for each complete tree of height $i > 0$, such that if $i \rightarrow \infty$, the probability of the root being occupied converges to $\frac{\omega}{1+\omega}$. Later in this section we will exploit such a construction to attain in full the conclusion of Part 2b of Theorem 1.

As a first observation, note that, the Gibbs measure for the hard-core model on T_i with boundary condition Γ is the same as the Gibbs measure for the hard-core model (with the same activity λ) on the tree T obtained from T_i by deleting all of the leaves as well as the parent of each (occupied) leaf $v \in \Gamma$. It will be convenient to work directly with such “trimmed” trees, rather than the complete tree with boundary condition. Having this in mind, our construction will be inductive in the following way. We will define a sequence of (trimmed) trees $\{(L_i, U_i)\}_{i \geq 0}$ such that L_{i+1} is comprised of s_{i+1} copies of U_i and $b - s_{i+1}$ copies of L_i with $\{s_i\}_{i \geq 1}$ properly chosen. Similarly, U_{i+1} is comprised of t_{i+1} copies of U_i and $b - t_{i+1}$ copies of U_i , with $\{t_i\}_{i \geq 1}$ properly chosen.

We will show that, for either $T_i^* = L_i$, or $T_i^* = U_i$, it is the case that the ‘ Q ’-value, defined as:

$$Q(T_i^*) = \frac{\mu_{T_i^*}(\sigma(r) = 1)}{\omega \mu_{T_i^*}(\sigma(r) = 0)},$$

where $\mu_{T_i^*}(\cdot)$ is the hard-core measure on the trimmed tree T_i^* , satisfies $Q(T_i^*) \rightarrow 1$. Note that if $Q(T_i^*) = 1$, then the probability of the root being occupied is $\omega/(1+\omega)$ as desired. To attain this, we will construct L_i and U_i in such a way that $Q(U_i) \geq 1$ and $Q(L_i) \leq 1$.

The recursion for $Q(L_{i+1})$ can be derived easily as

$$Q(L_{i+1}) = \frac{(1+\omega)^b}{(1+\omega Q(U_i))^{s_{i+1}}(a+\omega Q(L_i))^{b-s_{i+1}}},$$

and a similar equation holds for $Q(U_{i+1})$ by replacing s_{i+1} with t_{i+1} .

To keep the construction simple, we inductively define the appropriate t_i and s_i , so that once L_i and U_i are given, we let t_{i+1} be the minimum choice so that the resulting Q -value is ≥ 1 , more precisely, we let:

$$t_{i+1} = \arg \min_{\ell} \{Q = \frac{(1+\omega)^b}{(1+Q(U_i))^\ell(1+\omega Q(L_i))^{b-\ell}} : Q \geq 1\}.$$

$$\text{And similarly, we let: } s_{i+1} = \arg \max_{\ell} \{Q = \frac{(1+\omega)^b}{(1+Q(U_i))^\ell(1+Q(L_i))^{b-\ell}} : Q \leq 1\}.$$

The recursion starts with U_1 being the graph of a single node and L_1 being the empty set, so that $Q(U_1) = \lambda/\omega$ and $Q(L_1) = 0$. Observe that, by definition, $s_{i+1} \in \{t_{i+1}, t_{i+1} + 1\}$ and that the construction guarantees that the values $Q(L_i)$ are at most 1, and the values $Q(U_i)$ are at least 1. The following simple lemma justifies the correctness of our construction.

Lemma 10.

$$\lim_{i \rightarrow \infty} Q(U_i)/Q(L_i) = 1.$$

Proof. It is easy to see that either $t_i = s_i$ (meaning that $Q(L_i) = Q(U_i) = 1$), or $t_i = s_i - 1$, which implies that

$$\frac{Q(U_i)}{Q(L_i)} = \frac{1+\omega Q(U_{i-1})}{1+\omega Q(L_{i-1})} < \frac{Q(U_{i-1})}{Q(L_{i-1})}.$$

So the ratio is shrinking. Suppose the limit is not 1 but some value $q > 1$. Then,

$$\frac{Q(U_{i-1})}{Q(L_{i-1})} - \frac{Q(U_i)}{Q(L_i)} = \frac{Q(U_{i-1}) - Q(L_{i-1})}{(1+\omega Q(L_{i-1}))Q(L_{i-1})}.$$

Since $Q(U_i)/Q(L_i) > q$ and $Q(L_i) \leq 1$, we have

$$\frac{Q(U_{i-1}) - Q(L_{i-1})}{(1+\omega Q(L_{i-1}))Q(L_{i-1})} \geq \frac{(q-1)Q(L_{i-1})}{Q(L_{i-1})(1+\omega)} = \frac{q-1}{1+\omega},$$

which is a constant.

Therefore as long as $q > 1$, we show that the difference between the ratios for each step i is at least some constant which is impossible. Hence the assumption is false. \square

By this lemma, it is easy to check that if we let T_i^* to be equal to either U_i or L_i , then $Q(T_i^*) \rightarrow 1$. Indeed, we can show that the additive error decreases exponentially fast. The following lemma indicates that this is the case for $\omega < 1$ (although a similar result holds for any ω).

Lemma 11. Let ϵ_i^+ be the value of $Q(U_i) - 1$ and let ϵ_i^- be the value of $1 - Q(L_i)$, then

$$\epsilon_{i+1}^+ + \epsilon_{i+1}^- \leq \omega(\epsilon_i^+ + \epsilon_i^-).$$

Proof. We can rewrite the expression

$$(1 + \omega)^b / (1 + \omega Q(U_i))^j (1 + \omega Q(L_i))^{b-j}$$

as

$$\frac{1}{(1 + \frac{\omega}{1+\omega}\epsilon_i^+)^j (1 - \frac{\omega}{1+\omega}\epsilon_i^-)^{b-j}}.$$

Now, let k be the biggest index over $[b]$ such that the denominator of the previous expression is less than 1 (thus, $k + 1$ will be the least index such that the denominator is greater than 1). Then,

$$\begin{aligned} \epsilon_{i+1}^+ + \epsilon_{i+1}^- &= \frac{1}{(1 + \frac{\omega}{1+\omega}\epsilon_i^+)^k (1 - \frac{\omega}{1+\omega}\epsilon_i^-)^{b-k}} - \frac{1}{(1 + \frac{\omega}{1+\omega}\epsilon_i^+)^{k+1} (1 - \frac{\omega}{1+\omega}\epsilon_i^-)^{b-k-1}} \\ &= \frac{\frac{\omega}{1+\omega}(\epsilon_i^+ + \epsilon_i^-)}{(1 + \frac{\omega}{1+\omega}\epsilon_i^+)^{k+1} (1 - \frac{\omega}{1+\omega}\epsilon_i^-)^{b-k}} \\ &\leq \frac{\frac{\omega}{1+\omega}(\epsilon_i^+ + \epsilon_i^-)}{1 - \frac{\omega}{1+\omega}\epsilon_i^-} \quad (\text{by the property of } k + 1) \\ &\leq \omega(\epsilon_i^+ + \epsilon_i^-). \end{aligned}$$

□

Coming back to the original tree-boundary notation, let Γ_h^1 be the boundary corresponding to the trimming of the tree U_h and let Γ_h^2 be the boundary corresponding to the trimming of the tree L_h . By our construction, for any vertex v on the tree of height h , the measure from μ_{h,Γ_h^1} (or μ_{h,Γ_h^2}) projected onto the space of the independent sets of the subtree rooted at v with the boundary condition corresponding to the correct part of Γ and the parent of v being unoccupied is either μ_{i,Γ_i^1} or μ_{i,Γ_i^2} , where i is the distance of v away from the leaves on T_h . Conditioning on the parent of v being unoccupied, in the broadcast process defined in the Introduction, we would occupy v with probability $\omega/(1 + \omega)$. Therefore, in the above construction, the probability v is occupied (or rather unoccupied) is close to the desired probability, and the error will decay exponentially fast with the distance from the leaves. This is formally stated in the following corollary of Lemma 11.

Corollary 12. Given any $\omega < 1$ and the complete tree of height i , for Γ equal to Γ_i^1 or Γ_i^2 inductively constructed above, we have

$$\left| \mu_{i,\Gamma}(\sigma(r) = 0) - \frac{1}{1 + \omega} \right| \leq \omega^{i-1} \lambda / b.$$

Throughout the rest of this section it is assumed that we are dealing with the boundary conditions $\{\Gamma_h^1\}_{h \in \mathbf{N}}$ and $\{\Gamma_h^2\}_{h \in \mathbf{N}}$ constructed above. We will then show that for every

$\omega = (1 + \delta) \ln b/b$ under these two boundary conditions, the Glauber dynamics on the hard-core model slows down, whenever $\delta > 0$. As we know from Corollary 12, the error of the marginal goes down very fast, so that roughly we can think of the marginal distribution of the configurations on the tree from the root to the vertices a few levels above the leaves as being close to the broadcasting measure. In fact, by following the same proof outline as we did in Section 4, we are able to prove the same lower bound in the hard-core model for these boundaries. To do that we need a slight generalization of the reconstruction algorithm and extensions of the corresponding lemmas used in that section to handle the errors in the marginal probabilities.

To generalize the notion of a reconstruction algorithm to the case of a boundary condition we need to add an extra parameter ℓ depending only on ω and b . We will essentially ignore the bottom ℓ levels in the analysis, and we will use that for the top $h - \ell$ levels the marginal probabilities are close to those on the broadcasting tree. We define a *reconstruction algorithm with a parameter ℓ* for the tree T_h with boundary condition Γ as a function $A_\ell : \Omega(L_{h-\ell}) \rightarrow \{0, 1\}$. The algorithm A_ℓ takes the configurations of the vertices at height $h - \ell$ as the input and tries to compute the configuration at the root. For any $\sigma \in \Omega(T_{h,\Gamma})$, the sensitivity is defined as: $S_{\ell,A}(\sigma) = \frac{1}{n} \# \{v \in L_{h-\ell} : A_\ell(\sigma_{h-\ell}^v) \neq A_\ell(\sigma_{h-\ell})\}$. The average sensitivity of the algorithm at height $h - \ell$ with respect to the boundary Γ is defined as: $\bar{S}_{\ell,A}^\Gamma = \mathbb{E}_\sigma [S_{\ell,A}(\sigma) \mathbf{1}(A_\ell(\sigma_{h-\ell}) = 1)]$. And the effectiveness is defined as:

$$r_{\ell,A}^\Gamma = \min_{x \in \{0,1\}} [\mu_{h,\Gamma}(A_\ell(\sigma_{h-\ell}) = x \text{ and } \sigma(r) = x) - \mu_{h,\Gamma}(A_\ell(\sigma_{h-\ell}) = x) \mu_{h,\Gamma}(\sigma(r) = x)].$$

We can show the analog of Theorem 13 in this setting.

Theorem 13. *Suppose that A_ℓ is an effective reconstruction algorithm. Then, it is the case that the spectral gap c_{gap} of the Glauber dynamics for the hard-core model on the tree of height h with boundary condition Γ , satisfies $c_{\text{gap}} = O(\bar{S}_{\ell,A}^\Gamma)$, and hence the relaxation time of this Glauber dynamics satisfies $T_{\text{relax}} = \Omega(1/\bar{S}_{\ell,A}^\Gamma)$.*

To bound the average sensitivity for the boundary conditions Γ_h^1 and Γ_h^2 constructed above, we again use the same BW algorithm as we analyzed for the broadcasting tree. As in Eq.(2) and (3), it is again enough to bound the probability

$$P_{\ell,\text{BW}}^\Gamma := \mu_{h,\Gamma_h}(\text{BW}_\ell(\sigma_{h-\ell}) = 1 \text{ and } \text{BW}_\ell(\sigma_{h-\ell}^{\hat{u}}) = 0)$$

for a fixed vertex \hat{u} at a distance ℓ from the leaves, although in this case, this probability will not be the same for all \hat{u} . Let the path \mathcal{P} from \hat{u} to the root r be $u_0 = \hat{u} \rightsquigarrow u_1 \rightsquigarrow \dots \rightsquigarrow u_{h-\ell} = r$, and for each $i > 0$ and $j \in \{1, \dots, b\}$, let $w_{i,j}$ be defined similarly as in Section 4. Further, let $\Gamma_{i,j}$ be the boundary condition Γ_h restricted to the subtree $T_{w_{i,j}}$ of T_h rooted at the vertex $w_{i,j}$. These subtrees are of height $i + \ell - 1$ for each i . Note that, by our construction of the boundary conditions, for each fixed i , $\Gamma_{i,j} = \Gamma_{i+\ell-1}^1$ or $\Gamma_{i,j} = \Gamma_{i+\ell-1}^2$. The probability $P_{\ell,\text{BW}}^\Gamma$ can be calculated by the following lemma, which is the analog of Lemma 5 for the broadcasting tree.

Lemma 14.

$$P_{\ell,\text{BW}}^\Gamma \leq \mathbb{E}_\sigma \left[\prod_{i>0:\sigma(u_i)=0} \prod_{j=2}^b \Pr_{\eta \sim \mu_{i+\ell-1,\Gamma_{i,j}}} [A_\ell(\eta) = 0] \right],$$

where the expectation is over the measure μ_{h,Γ_h} , and for each i, j , η is a random configuration on the subtree rooted at $w_{i,j}$ with the probability measure $\mu_{i+\ell-1,\Gamma_{i,j}}$.

The proofs of Theorem 13 and Lemma 14 use the same proof approach as for Theorem 4 and Lemma 5 respectively. However, to bound $\Pr_\eta[A_\ell(\eta) = 0]$ for every $i > 0$, in spite of going along the lines of Lemma 6, the proof does require extra care to deal with the errors in the marginal probabilities which were bounded in Corollary 12. In particular, we will establish the following lemma to upper bound $\Pr_{\eta \sim \mu_{i+\ell-1,\Gamma_{i,j}}}[A_\ell(\eta) = 0]$ for each $i > 0$. Here and throughout the text, we define $\ell(\lambda, b)$ to be the minimum ℓ such that for all $i \geq \ell$,

$$\Pr_{\eta \sim \mu_{i,\Gamma_i^2}}[\eta(r) = 0] \leq \frac{1}{1+\omega} \exp\left(\frac{1.01(\omega b)^2}{\lambda}\right).$$

The existence of such constant $\ell(\lambda, b)$ is guaranteed by Lemma 10, also from Corollary 12 we can deduce a explicit value for $\ell(\lambda, b)$, provided that $\omega < 1$.

Lemma 15. *Given any $\delta > 0$, and $i \geq \ell(\lambda, b) = \ell$, then both $\Pr_{\eta \sim \mu_{i,\Gamma_i^1}}[A_\ell(\eta) = 0]$ and $\Pr_{\eta \sim \mu_{i,\Gamma_i^2}}[A_\ell(\eta) = 0]$ are upper bounded by $\frac{1.01^{1/b}}{1+\omega}$ for any $b \geq b_0(\delta)$.*

And also it is not hard to show that the BW algorithm under this setting is effective.

Proposition 16. *The BW reconstruction algorithm is effective to recover the configuration at the root from the configurations at distance $\ell(\lambda, b)$ from the leaves.*

Then, we are able to again bound $\bar{S}_{\ell,\text{BW}}^\Gamma$ for $\Gamma = \Gamma_h^1$ or Γ_h^2 , proving the following theorem, which completes the proof of Part 2b in Theorem 1. Interested readers can look up Section 5.1 for the complete proofs.

Theorem 17. *Let $\delta > 0$, and let $\omega = (1 + \delta) \ln b / b$. For all $b \geq b_0(\delta)$, it is the case that*

$$T_{\text{relax}} = \Omega(n^d), \quad \text{where } d = \left(1 + \frac{\ln(\lambda/(1.01\omega b)^2)}{2 \ln b}\right).$$

5.1 Proofs.

Proof of Lemma 15. Let $f_{i,1}$ denote $\Pr_{\eta \sim \mu_{i,\Gamma_i^1}}[A_\ell(\eta) = 0]$ and let $f_{i,2}$ denote $\Pr_{\eta \sim \mu_{i,\Gamma_i^2}}[A_\ell(\eta) = 0]$. Let $\bar{t}_i = b - t_i$ and $\bar{s}_i = b - s_i$ for simplicity. Now, recall the recurrences given in Lemma 6, which in this case take the form

$$\begin{aligned} f_{i+1,1} &= \Pr_{\eta \sim \mu_{i,\Gamma_i^1}}[\eta(r) = 1] \left(1 - \left(1 - f_{i-1,1}^{t_i} f_{i-1,2}^{\bar{t}_i}\right)^{t_{i+1}} \left(1 - f_{i-1,1}^{s_i} f_{i-1,2}^{\bar{s}_i}\right)^{\bar{t}_{i+1}}\right) \\ &\quad + \Pr_{\eta \sim \mu_{i,\Gamma_i^1}}[\eta(r) = 0] \left(1 - f_{i,1}^{t_{i+1}} f_{i,2}^{\bar{t}_{i+1}}\right), \\ f_{i+1,2} &= \Pr_{\eta \sim \mu_{i,\Gamma_i^2}}[\eta(r) = 1] \left(1 - \left(1 - f_{i-1,1}^{t_i} f_{i-1,2}^{\bar{t}_i}\right)^{s_{i+1}} \left(1 - f_{i-1,1}^{s_i} f_{i-1,2}^{\bar{s}_i}\right)^{\bar{s}_{i+1}}\right) \\ &\quad + \Pr_{\eta \sim \mu_{i,\Gamma_i^2}}[\eta(r) = 0] \left(1 - f_{i,1}^{s_{i+1}} f_{i,2}^{\bar{s}_{i+1}}\right). \end{aligned}$$

And the base cases are:

$$\begin{aligned} f_{\ell,1} &= \Pr_{\eta \sim \mu_{\ell, \Gamma_{\ell}^1}} [\eta(r) = 0], \quad f_{\ell,2} = \Pr_{\eta \sim \mu_{\ell, \Gamma_{\ell}^2}} [\eta(r) = 0], \\ f_{\ell+1,1} &= \Pr_{\eta \sim \mu_{\ell+1, \Gamma_{\ell+1}^1}} [\eta(r) = 0] \left(1 - f_{\ell,1}^{t_{\ell+1}} f_{\ell,2}^{\bar{t}_{\ell+1}}\right), \\ f_{\ell+1,2} &= \Pr_{\eta \sim \mu_{\ell+1, \Gamma_{\ell+1}^2}} [\eta(r) = 0] \left(1 - f_{\ell,1}^{s_{\ell+1}} f_{\ell,2}^{\bar{s}_{\ell+1}}\right). \end{aligned}$$

Our purpose now, is to show by induction that $f_{i,1}, f_{i,2} \leq \frac{1.01^{1/b}}{1+\omega}$ for all $i \geq \ell$. The base case is simple:

$$f_{\ell+1,1} \leq f_{\ell,1} \leq \Pr_{\eta \sim \mu_{\ell, \Gamma_{\ell}^1}} [\eta(r) = 0] \leq \frac{1}{1+\omega} \exp\left(\frac{1.01(\omega b)^2}{\lambda}\right),$$

and the last term is less or equal to $\frac{1.01^{1/b}}{1+\omega}$ for $b \geq b_0(\delta)$ [Lemma 8]. Similarly, it is the case that $f_{\ell+1,2} \leq f_{\ell,2} \leq \frac{1.01^{1/b}}{1+\omega}$. Now, in general, assuming the inductive hypothesis, we get from the above recurrence, that

$$f_{i+1,1}^b \leq \left[\frac{\omega}{1+\omega} \left(1 - \left(1 - \frac{1.01\omega}{\lambda}\right)^b\right) + \frac{1}{1+\omega} \right]^b \exp\left(\frac{1.01(\omega b)^2}{\lambda}\right),$$

where the first term, just as deduced in the proof of Lemma 6, is dominated by $\frac{\exp(1.01(\omega b)^2/\lambda)}{(1+\omega)^b}$. Now, the hypothesis follows for $f_{i+1,1}$ (and seemingly for $f_{i+1,2}$), due to the fact that $\exp(2(1.01)(\omega b)^2/\lambda) \leq 1.01$ for $b \geq b_0(\delta)$, proving the induction. \square

Proof of Proposition 16. Notice the formulas,

$$\begin{aligned} \mu_{h, \Gamma_h^1}(A(\sigma) = 0 : \sigma(r) = 0) &= 1 - \left[\mu_{h-1, \Gamma_{h-1}^1}(A(\sigma) = 0) \right]^{t_h} \left[\mu_{h-1, \Gamma_{h-1}^2}(A(\sigma) = 0) \right]^{\bar{t}_h} \\ \mu_{h, \Gamma_h^1}(A(\sigma) = 1 : \sigma(r) = 1) &= \left[1 - \left(\mu_{h-2, \Gamma_{h-2}^1}(A(\sigma) = 0) \right)^{t_{h-1}} \left(\mu_{h-2, \Gamma_{h-2}^2}(A(\sigma) = 0) \right)^{\bar{t}_{h-1}} \right]^{t_h} \\ &\quad \cdot \left[1 - \left(\mu_{h-2, \Gamma_{h-2}^1}(A(\sigma) = 0) \right)^{s_{h-1}} \left(\mu_{h-2, \Gamma_{h-2}^2}(A(\sigma) = 0) \right)^{\bar{s}_{h-1}} \right]^{\bar{t}_h}, \end{aligned}$$

whith similar expressions for $\mu_{h, \Gamma_h^2}(\cdot)$. Now, from these recurrences and the bounds stated in Lemma 15, we deduce that

$$\begin{aligned} \mu_{h, \Gamma_h^1}(A(\sigma) = 0, \sigma(r) = 0) - \mu_{h, \Gamma_h^1}(A(\sigma) = 0) \mu_{h, \Gamma_h^1}(\sigma(r) = 0) \\ = \Omega\left(1 - \frac{1.01}{(1+\omega)^b} - \frac{1.01^{1/b}}{1+\omega}\right) \gg 0 \end{aligned}$$

With the same result holding for $\mu_{h, \Gamma_h^2}(\cdot)$. \square

Proof of Theorem 17. It goes along the lines of the proof of Theorem 7. Here, we take ℓ as $\ell(\lambda, b)$, as in Lemma 15. Now, due to Lemma 14, we have that

$$\bar{S}_{\ell, \text{BW}}^\Gamma = O \left(\mathbb{E} \left[\left(\frac{1.01\omega(1+\omega)}{\lambda} \right)^{\#\{i: \sigma(u_i)=0\}} \right] \right),$$

and using the second statement of Lemma 9, we have that

$$\mathbb{E} \left[\left(\frac{1.01\omega(1+\omega)}{\lambda} \right)^{\#\{i: \sigma(u_i)=0\}} \right] \lesssim \left(\frac{1.01\omega \exp \left(\frac{1.01(\omega b)^2}{\lambda} \right)}{2\lambda} \left[1 + \sqrt{1 + \frac{4\lambda}{1.01 \exp \left(\frac{1.01(\omega b)^2}{\lambda} \right)}} \right] \right)^{h-\ell},$$

where the previous term is dominated by $\left(1.01 \frac{\omega}{\lambda^{1/2}} \right)^{h-\ell}$. And just as in the proof of Theorem 7,

$$\bar{S}_A = O \left(\left[\frac{1.01\omega}{\lambda^{1/2}} \right]^h \right) = O \left(n^{-\left[1 + \frac{\ln(\lambda/(1.01\omega b)^2)}{2 \ln b} \right]} \right).$$

Now, from Proposition 16, the BW algorithm is effective for $\omega > (1+\delta) \ln b/b$, $b > b_0(\delta)$, therefore Theorem 13 applies. The conclusion follows. \square

6 Upper Bounds of the Relaxation Time via the Coupling Method

We will use the coupling technique in some of our proofs which upper bound the relaxation time and the mixing time. The mixing time T_{mix} for the Glauber dynamics is defined as the number of steps, from the worst initial state, to reach within variation distance $\leq 1/2e$ of the stationary distribution. It is an elementary fact that the mixing time gives a good upper bound on the relaxation time (see, e.g., [18] for the following bound), we will use this fact in our upper bound proofs:

$$T_{\text{relax}} \leq T_{\text{mix}} + 1. \quad (4)$$

Given two copies (X_t) and (Y_t) of the Glauber dynamics, a coupling is a joint process (X_t, Y_t) such that the evolution of each component viewed in isolation is identical to the Glauber dynamics, see [18] for more background on the coupling technique. The Coupling Lemma [2] (c.f., [18, Theorem 5.2]) guarantees that if, there is a coupling and time $t > 0$, so that for every pair (X_0, Y_0) of initial states, $\Pr[X_t \neq Y_t \mid X_0, Y_0] \leq 1/2e$ under the coupling, then $T_{\text{mix}} \leq t$.

Before we show the main idea of proving the upper bound, let us introduction some notations for this section first. Let τ_ρ be the relaxation time of the following Glauber dynamics of the hard-core model on the star graph G , where ρ is a b dimensional vector. The dynamics is defined as: if the root is chosen, it will be occupied with probability $\lambda/(1+\lambda)$ if no leaf is occupied; if the leaf i is chosen, it will be occupied with probability ρ_i if the root is unoccupied. Therefore $\tau := \max_\rho \{\tau_\rho\}$ is defined as the worst case relaxation time over all the possible choice of ρ . Following the same block dynamics strategy [20] as in Section 2.3 of the paper by [3] (See also [19] and [30]), it is not hard to show that the

relaxation time of the above Glauber dynamics is exactly the same as that of the natural block dynamics which updates the configurations of a whole subtree of the root in one step, and hence the following lemma holds.

Lemma 18. *The relaxation time T_{rel} of the Glauber dynamics of the hard-core model on the complete tree of height H is upper bounded by τ^H for any boundary condition on the leaves.*

Note that, the relaxation time is quite sensitive with respect to the boundary conditions. Especially, in the paper by [22], they show that when the boundary conditions are even (or odd) meaning that occupied all the leaves when the height is even (odd) and unoccupied all the leaves when the height is odd (even), the mixing time is actually $O(n \ln n)$. In this paper we are dealing with any kind of boundary condition, and in the lower bound part, we show the boundary conditions that slow down the Glauber dynamics actually exist. The lower bound on the relaxation time for the Glauber dynamics under that boundary conditions roughly matches up with the upper bound here.

We need to bound the relaxation time τ of the Glauber dynamics on star graphs for different cases with respect to ρ . To do this, we first use the so-called maximum one step coupling to bound the mixing time and then by Eq.(4) we get an upper bound on the relaxation time τ . The maximal one-step coupling, originally studied for colorings by Jerrum [14] gives a way to upper bound the mixing time of the Glauber dynamics on general graphs. The coupling (X_t, Y_t) of the two chains is done by choosing the same random vertex v for changing the states at step t and maximizing the probability of the two chains choosing the same update for the state of v . Thus, if none of neighbors of v is occupied in neither X_t and Y_t , v will be occupied/unoccupied in both chains at time $t+1$ with the correct marginal probability. In all other cases, the update choices for $X_{t+1}(v)$ and $Y_{t+1}(v)$ are coupled arbitrarily. By analyzing the maximum one-step coupling, we will show a series of lemmas for different ρ , which give the upper bound on the relaxation time τ .

Lemma 19. *If $\sum \rho_i \leq 4 \ln \ln b$ and for all i , $\rho_i \leq 1 - 1/\ln b$, then $\tau = O(b^{1+o(1)})$, where $o(1)$ is a term that goes to zero as b goes to infinity.*

Lemma 20. *If $\sum \rho_i \geq 4 \ln \ln b$, then $\tau = O((\lambda + 1)b \ln b)$.*

Lemma 21. *If there exists an i such that $\rho_i > 1 - 1/\ln b$, then $\tau = O((\lambda + 1)b \ln b)$.*

The intuition behind is that the typical behaviors of the coupling chain change with respect to the leaves marginal probability ρ . When ρ are all tiny (Lemma 19), the coupling chain has a large chance to have all the leaves unoccupied in both (X_t) and (Y_t) and hence can be coupled at the state where the root is occupied in both chains with a good probability; While when the sum of ρ is big (Lemma 20 and 21) suggesting that there is a good chance that one of the leaves is occupied always, the coupling chain is easier to get coupled once the root is not occupied in both chains. We delay the proofs of these lemmas in Section 6.1. By applying Lemma 18 to Lemma 19, 20 and 21, we get the conclusion that the relaxation time is upper bounded by $O(n^{1+\ln(\lambda+1)/\ln b + o_b(1)})$ for any $\lambda > 0$. Recall that the relationship between ω and λ is $\lambda = \omega(1 + \omega)^b$ and in this paper we are mainly interested in the cases when $\omega = (1 + \delta) \ln b / b$ for any constant $\delta > -1$. Hence, in terms of ω , if $-1 < \delta \leq 0$ the relaxation time is upper bounded by $n^{1+o_b(1)}$ and if $\delta > 0$ the relaxation time is upper bounded by $n^{1+\delta+o_b(1)}$, which proves Theorem 1.

6.1 Proofs.

Without loss of generality, we assume that the root is unoccupied in X_0 and occupied in Y_0 . Readers will see later in the proofs that these are indeed the worst cases scenarios. We prove the lemmas by analyzing the coupling in rounds, where each round consists of $T := 20b \ln b$ steps. The following analysis says that if in each round we have a good probability of coalescing (i.e., achieving $X_t = Y_t$), then we will have a good upper bound on the mixing time (and hence the relaxation time). Suppose that in the coupling process, starting from any pair of initial states, after time T , with probability P_T we have $X_T = Y_T$. By repeatedly applying this assumption i many times we have, for all (x_0, y_0) ,

$$\Pr[X_{2iT} \neq Y_{2iT} \mid X_0 = x_0, Y_0 = y_0] \leq (1 - P_T)^{2i} \leq 1/2e$$

for $i = 1/P_T$. Therefore, by applying the Coupling Lemma, mentioned in Section 2, the mixing time is $O(b \ln b / P_T)$. Now, the only thing left is to lower bound P_T for different ρ assuming that the root $r \notin X_0$ and $r \in Y_0$. Let us define for any configuration $X_t \in \Omega(G)$, $\|X_t\| := |\{\ell \in V(G) : \deg(\ell) = 1 \text{ and } \ell \in X_t\}|$, the number of leaves of the star graph G that are in the independent set.

Proof of Lemma 19. In this case, we will try to couple all of the leaves to unoccupied and then couple the root. Let T_0 be the last time the root is chosen to change the state in the T steps running of the coupling chain. It is a simple fact from the coupon collector problem that with high probability, $T_0 > 10b \ln b$ and all the leaves have been chosen at least once before T_0 . Note that throughout this section “with high probability” means the probability goes to 1 as b goes to infinity. Conditioning on this, consider the following process (B_t) :

- $B_t \subseteq V(G)$;
- For each time t the process (B_t) chooses a leaf v_i to update: $B_{t+1} = B_t \cup v_i$ with probability ρ_i and $B_{t+1} = B_t \setminus \{v_i\}$ with probability $1 - \rho_i$;
- The process will ignore any update of the root and the state of the root at any time.

By the conditioning we assume, we know that after $10b \ln b$ steps, every leaf has been updated at least once. Therefore the chance that all of the leaves are not in B_t (i.e. (B_t) is an empty set) is

$$\prod_{i=1}^b (1 - \rho_i) \geq \prod_{i=1}^b e^{-\rho_i \cdot \ln \ln b} \geq e^{-4 \ln^2 \ln b},$$

where $1 - x > e^{-x \cdot \ln \ln b}$ holds when $x < 1 - 1/\ln b$. There is a straightforward coupling of (X_t) and (B_t) such that for any $t \geq 0$, $\|X_t\| \leq |B_t|$. And also, by the nature of the maximum one-step couplings with the assumption $r \notin X_0$ and $r \in Y_0$, for any $t \geq 0$, $\|X_t\| \geq \|Y_t\|$. Therefore, we can conclude that with probability at least $e^{-4 \ln^2 \ln b}$, at time $T_0 - 1$, all the leaves are unoccupied in both X and Y , and hence with probability 1, when the coupling chain chooses the root to update at time T_0 , we have $X_{T_0} = Y_{T_0}$. In conclusion, we show that with probability at least $e^{-4 \ln^2 \ln b}$, we have $X_T = Y_T$, which implies that the mixing time and hence the relaxation time is $O(b \ln b \cdot e^{4 \ln^2 \ln b}) = O(b^{1+o_b(1)})$, where $o_b(1)$ is a $O(\ln^2 \ln b) / \ln b$ function. \square

Proof of Lemma 20. In this case, we want to first unoccupy the root in both chains and then couple the leaves. The key observation is that once the root is not occupied, it will not be occupied again since there is a good chance that one of the leaves is always occupied and hence “blocking” the root from being occupied. First of all, it is easy to see that in the first b steps, the coupling chain has a positive probability of choosing the root to change the state and at that moment, the chance of the root being unoccupied in both chains is at least $1/(\lambda+1)$. We denote this as event \mathcal{E}_1 . Next, we want that in the following b steps, with positive probability, the root will not be chosen to change the state, therefore the chain chooses b leaves to change the states during these b steps. Let the set of leaves that are chosen during these b steps be S . We want to argue that with positive probability, $\sum_{i \in S} \rho_i > c_0 \ln \ln b$ for some constant $c_0 > 1$ so that S is a set of good representatives of all the leaves. Let this be the event \mathcal{E}_2 . By using the fact that for each leaf, the indicator random variable of whether the leaf is chosen or not during these b steps are negatively associated to each other (c.f., Theorem 14 in [9]), we can still use the following Hoeffding bound (Theorem 2 in [13]) by Proposition 7 in [9].

Theorem 22. *Let X_1, \dots, X_n be independent (or negatively associated) random variables with $a_i \leq X_i \leq b_i$. Let $X = \sum_i X_i$ and $\mu = E[X]$. Then the following inequality holds*

$$\Pr[|X - \mu| \geq t] \leq 2 \exp\left(-\frac{2t^2}{\sum_{i=1}^n (a_i - b_i)^2}\right).$$

In our case, $X_i = \rho_i$ if the leaf i is chosen in b steps and otherwise zero. Therefore, since in our case $\sum_{i=1}^n (a_i - b_i)^2 \leq (\sum_{i=1}^n (b_i - a_i))^2 = (4 \ln \ln b)^2$, $\mu \geq 4(1 - 1/e) \ln \ln b$ and $t = \delta \mu$ for some properly chosen $\delta > 0$, it is straightforward to show that with positive probability, the event \mathcal{E}_2 happens. Note that the events \mathcal{E}_1 and \mathcal{E}_2 are actually independent. And from now on, we are conditioning on \mathcal{E}_1 and \mathcal{E}_2 .

For each $t > 2b$, let $A_t := \{\ell \in S : \ell \in X_t \text{ and } \ell \in Y_t\}$ be the set of leaves in S such that they are in the independent set at time t in both X_t and Y_t . Let the stopping time T_s be the first time $t > 2b$ such that $A_t = \emptyset$ and the root is chosen. If we can show that $\Pr[T_s < 2b \ln b] < 1/2$, then with positive probability, the root is always blocked from changing to occupied since $A_t \neq \emptyset$. Hence once the chain chooses all the leaves during $2b \ln b - 2b$ steps, we will have $X_T = Y_T$. Finally, because the events \mathcal{E}_1 and \mathcal{E}_2 happen with probability $\Omega(1/(\lambda+1))$, we can conclude that with probability $\Omega(1/(\lambda+1))$, $X_T = Y_T$.

In order to show that $\Pr[T_s < 2b \ln b] < 1/2$, we will use the same coupling strategy as in the last proof. Let (C_t) be a stochastic process that update the states of $|S|$ many independent vertices in the following way:

- The process starts at time $t = 2b + 1$ with a random starting configuration;
- For any t , $C_t \subseteq S$;
- For each time t the process (C_t) chooses a vertex $v \in V(G)$ randomly;
- If $v = v_i \in S$ then apply the following update rule: $C_{t+1} = C_t \cup v_i$ with probability ρ_i and $B_{t+1} = B_t \setminus \{v_i\}$ with probability $1 - \rho_i$.

Let the stopping time T_c be the first time $t > 2b$ such that $C_t = \emptyset$ and the root is chosen. We want to couple (C_t) and (X_t, Y_t) in such a way that $T_s > T_c$ for all runs and then if we can show that $\Pr[T_c < 2b \ln b] < 1/2$, by the coupling, we are done.

In fact, it is easy to show that $\Pr[T_c < 2b \ln b] < 1/2$ (any positive constant will do) by using union bound combining with the following two facts: for any fix time $t > 2b$, the probability that $C_t = \emptyset$ is upper bounded by $(\ln b)^{-c_0}$ with $c_0 > 1$; with high probability the root will be chosen at most $O(\ln b)$ times during T steps. Now we just need a valid coupling.

We couple (C_t) with the coupling chain (X_t, Y_t) from time $t = 2b + 1$ in the following way:

- Initially, for $t = 2b$, $v \in C_t$ if and only if $v \in A_t$.
- For any time t , both of them pick the same vertex v to update and if $v \in S$, $v \in C_t$ if and only if $v \in A_t$.

It is easy to verify that conditioning on the events \mathcal{E}_1 and \mathcal{E}_2 , this coupling is valid and $T_s > T_c$, which completes the proof. \square

Proof of Lemma 21. This case is the same as the last one. However, we can just use the leaf i to block the root since it has a very high probability of being occupied, i.e., for the probability bound concerning T_s , it is enough to bound the probability that at a given time t , the leaf i is occupied. \square

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